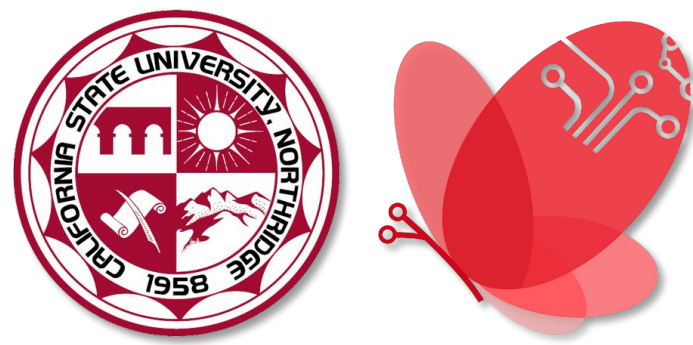


Research Objective



The purpose of this project is to **analyze the ratio of human operators** per agent, **propose models** for organizing teams, and include a **hierarchy system** to optimize human supervisory control. The goal of this project is to **organize teams of human operators** to supervise more agents without experiencing fatigue.

Research Approach

1. By **reviewing the literature** in multiple-agent systems and the team architectures that have been proposed previously, this study will compile variables that influence the human-robot ratio and strategies for manipulating these variables.
2. Through **semi-structured interviews** and **focus group discussions** with NASA scientists, this study will examine the real-world application of these strategies and test an architecture for organizing human-multiple-robot teams.
3. This research seeks to establish an architecture for **organizing human-robot teamwork** and identify the variables that influence the human-to-robot ratio.

Research Team

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