



Research Objective

- Design an interface system for the Intent Manager of the NASA Resilient Autonomy (RA) Project's Expandable Variable-Autonomy Architecture (EVAA), which is a hierarchal autonomous system framework that depends on deterministic systems with higher authority to protect against catastrophic piloting faults and allow a lower level certification for the machine learning sub-systems
- Evaluate Intent Manager interface system and make recommendations to NASA EVAA designers and engineers

Research Approach

- Create a RA testbed at ARCS by replicating NASA ground control station and EVAA hardware and software that will provide a flexible framework for autonomy algorithm research and will allow software development
- Formulate requirements (i.e., autonomy must express its intent to others) for the Intent Manager's Social Computer
- Design and prototype an interface system in the form of a Social Computer that has stand-alone processors for receiving discrete info from EVAA and multi-model triggering (e.g., lighting, tones, voice)
- Conduct human-in-the-loop simulation studies to evaluate the Social Computer interface system

Research Team

ARCS Fellow: Sarkis S. Mikaelian

ARCS Advisors:

- Li Liu, Ph.D., Computer Science;
- Nhut Ho, Ph.D., Systems engineering

NASA Collaborators:

- Mr. Nelson Brown, AFRC
- Mr. Mark Skoog, AFRC

