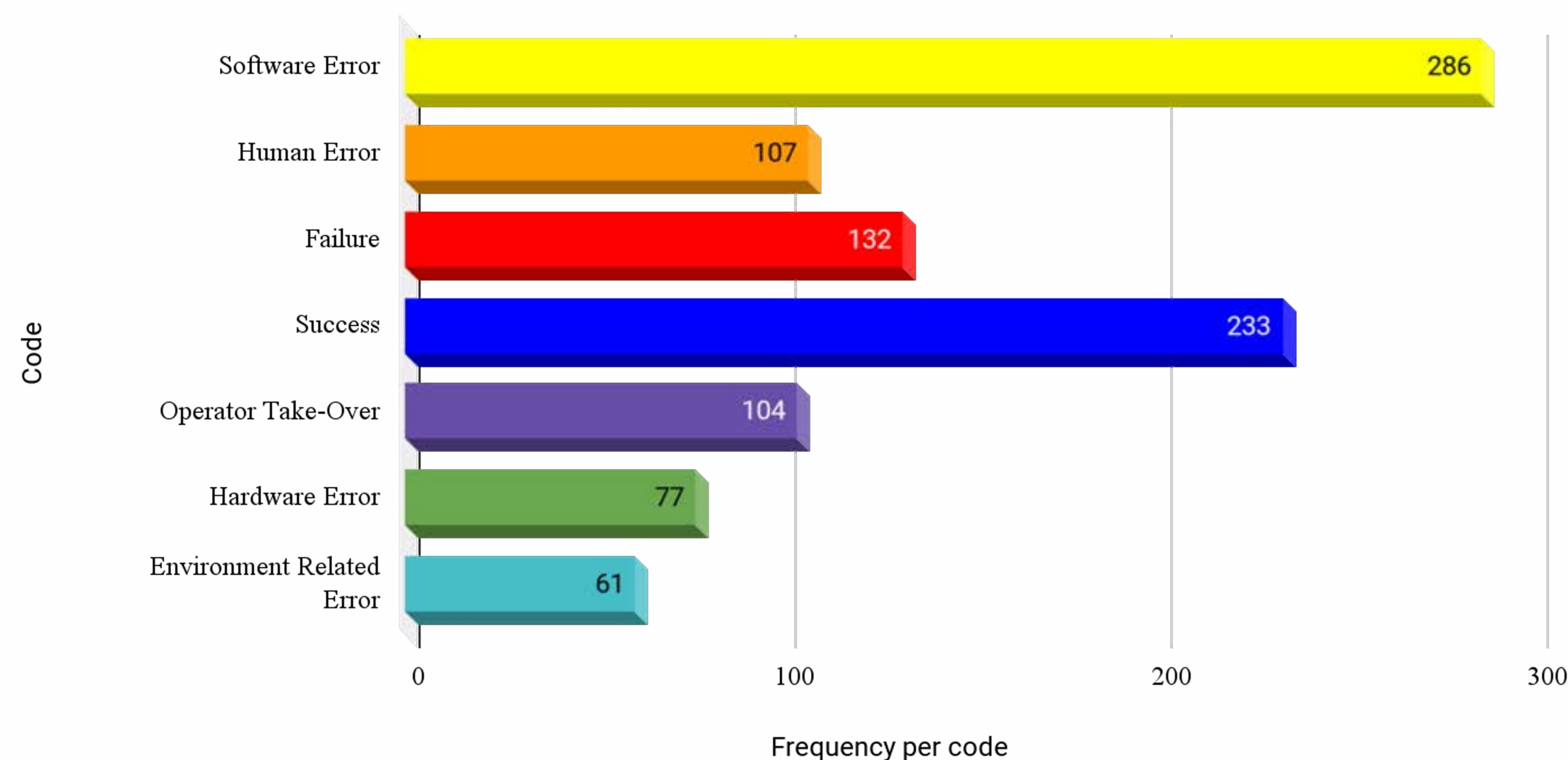


Figure 1. Photos representing heterogeneous human-machine teams within real systems, real users, and real consequences (R3).

Factors Influencing Trust in Human-Machine Teams

Fig 2: A visual representation of emerging themes in the interviews



Synopsis

- Study explores trust development in human-machine interactions using ethnographic, qualitative methods in real-world settings.
- Research focuses on heterogeneous human-machine teams (HMT) with different roles, capabilities, collocation, and collaboration durations.
- We investigate how these diverse factors influence trust and team performance in practical, real-world scenarios.

Research Objective

- Obtain foundational lessons and insights on how trust is calibrated and evolves over time.
- Identify how technology and non-technology-related factors (e.g., organizational, cultural, personal) influence the trust evolution.
- Validate extant theoretical trust models against trust calibration and evolution of heterogeneous Real World, Real Users, Real Consequences (R3) HMTs, and adapt or extend the models.
- Generate hypotheses for trust evolution and calibration in heterogeneous R3 HMT contexts.

Research Approach

- Use complementary qualitative methods for select R3 HMT at NASA JPL, including participant observation, surveys, and interviews (unstructured and semi-structured).
- Analyze data using a grounded theory approach, involving thematic coding and a constant comparative method to generate hypotheses and new theoretical models.
- Utilize an iterative case study method to refine design, preparation, and collection phases based on emergent themes or topics.

Research Results and Products

- Log data confirms our findings that knowledge of software is a high indicator of trust with R3 HMT.
- Zoom meetings and ritualistic practices created a strong sense of communitas, enhancing trust and social cohesion without physical proximity.
- Trust increases as humans become more grounded and take more ownership of robot behaviors/capabilities.
- Higher stakes, complexity, and asset risk in Mars 2020 HMT reduced trust in robot team members, leading to more cautious use of autonomous features.
- Hypothesis: The presence of a human safety operator in R3 HMT leads to more aggressive or risk-taking use of autonomous features.

Commercialization and/or Societal Impact Opportunities

- Develop a framework and guidelines to build trust in diverse Human-AI teams, emphasizing ethical AI design and responsible governance.
- Inform advanced operations concepts involving heterogeneous HMTs and related advanced autonomy technologies by prioritizing people for responsible AI.

Team Names & Collaborators

ARCS Students:

Zulma Lopez-Rodriguez, BS Psychology; Jordan Jannone, Instructional Technologist/Designer, Tseng College; Rachel Huerta, BS Psychology; Aniket Christi, Computer Science

Faculty:

Dr. Nhut Ho, Mechanical Engineering and Kevin Zemlicka, Academic Advisement, Anthropology & Psychology

NASA Collaborators:

Ben Morrell, Marcel Kaufmann, Mike Milano, JPL
Ali-akbar Agha-mohammadi, Olivier Toupet, Nelson Brown, Armstrong Flight Research Lab

Citations

Lyons, J. B., Sycara, K., Lewis, M., & Capiola, A. (2021). Human-Autonomy Teaming: Definitions, Debates, and Directions. *Frontiers in Psychology*, 12. <https://doi.org/10.3389/fpsyg.2021.589585>

Lee, J. D., & See, K. A. (2004). Trust in automation: designing for appropriate reliance. *Human Factors The Journal of the Human Factors and Ergonomics Society*, 46(1), 50-80. <https://doi.org/10.1518/hfes.46.1.50.30392>